

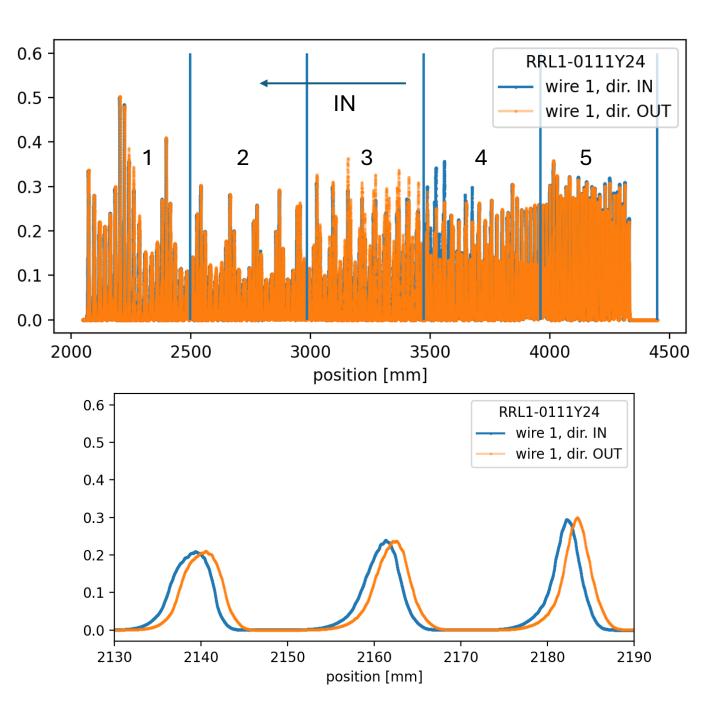
# Investigation of RRL signal shift between IN and OUT scan

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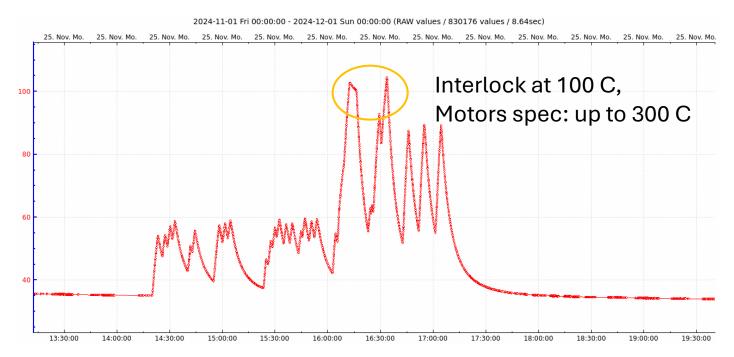
#### Context

- RRL measurements during movement IN and OUT do not overlap.
- Because of huge number of points wagon must stop 5 times in each direction to allow data transfer.
- Each stop lasts about 1.2 second.
- Time between stops (a segment): about 16.9 seconds.



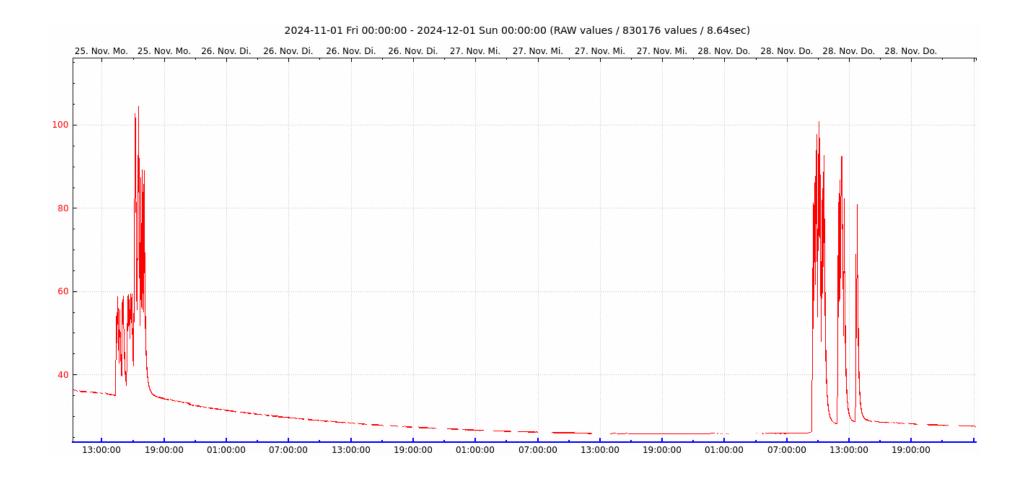
## Experiment

- If the IN-OUT shift is due to movement of the wagon due to pulling force of the cable tray, then breaks should be used during intermediate stops.
- The motor we use phytron VSS 33.200.1.2 does not have the break feature, but the controller can provide "holding current (Stoppstrom)" which should in principle prevent unintendent movement of the motor. "Holding current" flows through the motor all the time.
- We tried to apply "holding current" of 1.1 A (same as running current). Motor got quite hot!



# Experiment

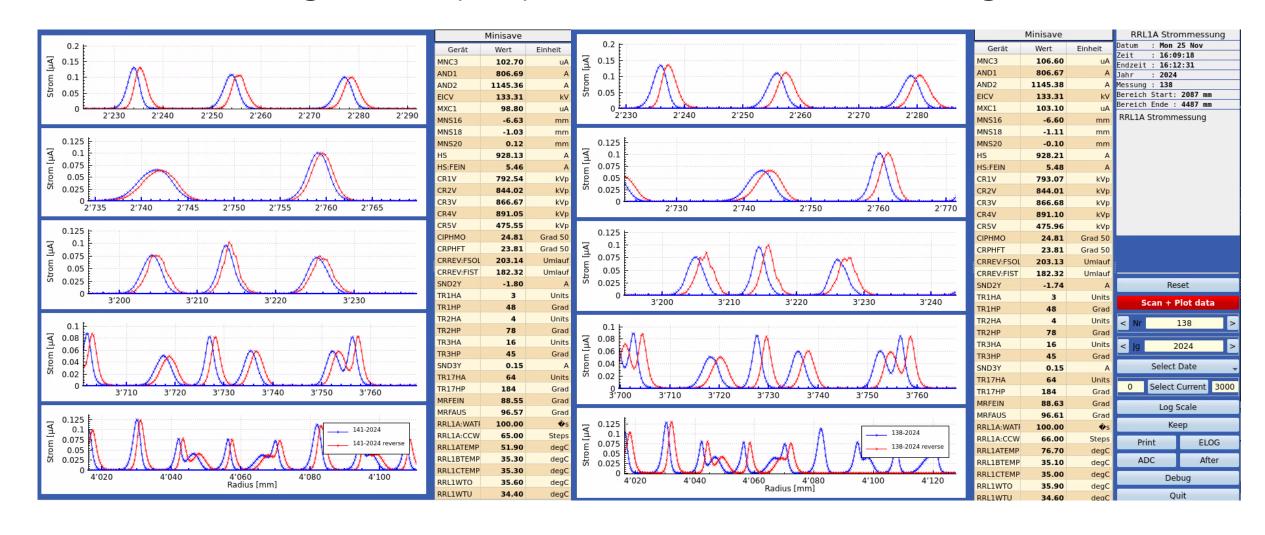
• Clearly something happened when holding current applied. All the scans afterwards are reaching higher temperatures!



# Experiment

without holding current (141)

#### with holding current



#### Other measurements

Also tried various motor settings

### Conclusions

- Holding current heats up the motor too much.
- It does not seem to have effect on IN-OUT shift.
- Need to investigate this phenomena during shutdown.
- Need to investigate what has changed with the motor during the experiment (spare motor ordered).