

Applications of machine learning in beam diagnostics

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Outline



- Introduction: what is Machine Learning?
- Some famous examples.
- Artificial Neural Networks.
- Theoretical background.
- Example 1: identification of quench-provoking loss patterns at LHC.
- Example 2: correction to measured beam profile distortion in Ionization Profile Monitor.
- Conclusions.



- Beam Diagnostics takes care of beam parameters measurements, for example: beam position, beam current, longitudinal and transverse profile, beam loss, tune, chromaticity, etc.
- Machine Learning techniques are also used in other aspects of accelerators, mainly control systems, machine tuning – not discussed here.
- Keep in mind that I am ML enthusiast, but not trained Machine Learning professional.





- Algorithms which can learn and make predictions on data, without explicit programming.
- The term by Arthur Samuel (IBM) in 1959.
- Machine learning is closely related to computational statistics and to mathematical optimization.
- Data mining is a sub-field of Machine Learning known as unsupervised learning.
- Expert systems are made of digitized/encoded expert knowledge. They are not Machine Learning algorithms.
 Still useful is there is little data available for training.
 Mixed systems are also available.

Examples of ML-based projects (I)





- x x o Jeopardy
- Go is difficult for algorithms because of number of configurations (>2x10¹⁷⁰, chess only \sim 5x10⁵²), atoms in the Universe ~ 10^{80} .
- The program uses Artificial Neural Network for learning and Monte Carlo Tree Search for decide about next move.
- > 1 year learning time, 183 MWh energy, excessive data sample – not the way human learns, but:
 - AlphaGo won against the highest-qualified humans.
 - It has exhibited creative skills making moves seldom done by humans.

Examples of ML-based projects (II)



- Neural Networks are used in physics analyses since ~1988.
- They were for instance used to reject background in Higgs boson search – but published analysis does not use ML.
- b-tagging:





show examples how Machine Learning techniques, mainly artificial neural networks (ANN), can be useful to solve everyday problems of accelerator physicist in domain of beam instrumentation.

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Artificial Neural Network

- Biologically inspired → Brain cells -> neurons, computation via connections and thus Networks
- > The basic node of ANNs is "Perceptron"

Perceptron parameters:

W

W

Input Layer

*X*₁

 X_k

 X_N

- Weights from the inputs (X) and bias (b)
- g is the activation function, a step-like function with a threshold

[https://www.wired.com/2016/03/took-neuroscientists -ten-years-map-tiny-slice-brain]







Hidden layers



Multi-layer perceptron



Each hidden layer and output layer node is a perceptron $o_i = g \left(\sum_{j=0}^{M} W_{ij} \left(g \left(\sum_{k=0}^{N} x_k W_{jk} + b_j \right) \right) + b_i \right)$

Adding "hidden" layer(s) allow non-linear target functions to be represented

Multi-layer perceptron (MLP)





• Carla P Gomes, Lecture Notes CS 4700: Foundations of Artificial Intelligence

Universal approximation theorem:

 Every bounded continuous "target" function can be approximated with arbitrarily small error, by network with single hidden layer [Cybenko 1989; Hornik et al. 1989]

If we have any unknown function, y = f(x), it can be approximated by:

$$o_i = g\left(\sum_{j=0}^M W_{ij}\left(g\left(\sum_{k=0}^N x_k W_{jk} + b_j\right)\right) + b_i\right)$$

Multi-layer perceptron (MLP)





Inner layers

How to design MLP topology for a given problem? How to find the weights? (train network)

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MLP Network design



For feed-forward MPL.

From: https://www.solver.com/training-artificial-neural-network-intro

- There is no best answer to the layout of the network for any particular application. There are general rules:
 - As the complexity between input and output increases, the number of the perceptrons in the hidden layer should also increase.
 - If the process being modeled is separable into multiple stages, then additional hidden layer(s) may be required. Otherwise additional layers may simply enable memorization of the training set, and not a general solution effective with other data.
 - The amount of training data sets an upper bound for the number of perceptrons in the hidden layer(s).
 If you use too many perceptrons the training set will be memorized.
 ->generalization of the data will not occur, making the network useless on new data sets.

- How it works:
 - Activation function g must be differentiable, eg. sigmoid or tanh.
 Initial weights chosen randomly.

For training record (or a batch of records) a cost function (or loss or error)
is calculated, for instance mean squared error:
(y-desired output, o-actual output)
$$E = \sum_{i=0}^{\infty} (y_i - o_i)$$

The cost function gradient is calculated for each layer:

$$\frac{\delta E}{\delta W_{ij}^1} = a_j Err_i g'(inp_i)$$

Repeat for new record (but you can use the same record later again)

MLP Network training

- Some algorithms known since 40's (Gauss Newton or Levenberg-Marquardt).
- Backpropagation with Gradient Descent developed in 70's - speeds up in ANN training - it triggered a wave of interest in ANN applications – still most popular.

$$o_i = g \left(\sum_{j=0}^{M} W_{ij} \left| g \left(\sum_{k=0}^{N} x_k W_{jk} + b_j \right) \right| + \right)$$

 $\frac{\delta E}{\delta W_{ik}^2} = x_k g'(inp_j) \sum_{i=0}^{M} W_{ij} Err_i g'(inp_i)$

2



Conditioning inputs and initial weights

- Weights initialization: Generate random initial weights [-1,1] and divide each of by the square root of the number of units in the larger layer.
- Inputs and targets to be normalized according to the used activation function (tanh: -1..1, sigmoid: 0...1), else some perceptrons will remain saturated (difficulty in learning).
- Tanh activation function of 1.00.50.50.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.00.0
- Rules of thumb: Start with two hidden layers with number of hidden units equal to (Input_num + Target_num)/2, avoid overfitting by regularization.
- If simple MLP is not good enough for the application, look further into literature!



Neural network Zoo





Source: Fjodor Van Veen, Asimov Institute, Utrecht

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Example 1: Pattern recognition in BLM signals



Beam Loss Monitors (BLMs) at LHC:

- Most high-power accelerators are equipped with BLM systems.
- LHC beam has energy of about 360 MJ per beam, equivalent to about 300 passenger cars on a motorway.
- Uncontrolled loss of even fraction of such a beam can damage equipment or quench a magnet.
- $^{\rm >}\,$ Therefore about 4000 BLMs are installed around LHC, ready to dump the beam within ~200 $\mu s.$





Example 1: LHC interaction points

- In order to focus the beams in the interaction point (experiment) special high-gradient quadrupoles are installed – called triplets.
- Beam-beam collisions produce interesting physics results and debris, which leak to triplets
- Due to that triplet magnet are constantly "heated" to about 30% of quench limit (~3 mW/cc).
- Only small variation of BLM signal corresponds to quench-provoking beam loss. What to do?





Example 1: How to recognize beam loss



- First idea: install BLM monitors inside the magnets, close to the coils.
 - Advantage: closer to the coil measurement corresponding better to the real coil heating
 - Disadvantages: difficult location, small space, no service possible, liquid helium environment, high integrated dose, technical risk due to additional structures inside magnet etc...
 - R&D and test installation done with silicon and diamond detectors, not very promising!



Test Artificial Neural Network patter recognition capacity!

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Example 1: Some code

- Python
- Google tensorflow library with keras interface:
 >pip install tensorflow
 >pip install keras
- Create ANN:



- Prepare data:
 - Debris: 100k events with independent random variation of each BLM signal by 10%
 - Loss: 100k events with independent random variation of each BLM signal by 50% MIXED with debris to a quench level.
- > Train: model.fit(traindata,trainlabel,nb_epoch=70)
- Run on new data: out_loss=model.predict(testdata)

that's it! 10 - 20 lines of code!



18 inputs (BLM signals)

dense_1_input: InputLayer

Example 1: Pattern recognition in BLM signals



Result:

Overlap: about 0.5% of quench-provoking losses undetected.

Compare it to standard method, for instance Mean Square Error between expected debris signal (D_{exp}) and signals at quench.

 $MSE = \Sigma (D_{exp,i} - S_i)^2$

To give more chances to classical signal we limit ourselves to 6 most sensitive BLMs. Otherwise it is the same data. Overlap: about **2%** of losses undetected.



10-1

10-2

10-3

0.05

0.10

0.15

MSE

0 20

0 25

0.30

Example 1: Pattern recognition in BLM signals



Lessons learned:

- It took < 1 day to perform this analysis: it is easy!</p>
- Without further optimization the results are better than (simplistic)
 "classical" approach.
- However this solution was finally not chosen, because people do not like "black boxes"...

Example 2: Correction of IPM signal distortion due to beam space-charge



Ionization Profile Monitor (IPM):

- Measures transverse profile of particle beam.
- Rest gas (pressure 10⁻⁸ mbar) is ionized by the beam.
- Electric field is used to transport electrons/ions to a detector.
- If electrons are used additional magnetic field is usually applied to confine their movement.





Example 2: Profile distortion in IPM





... instrumental effects such as camera tilt, optical point-spread-functions, point-spread functions due to optical system and multi-channel plate granularity etc, etc... come on top!

Example 2: Profile distortion in IPM





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Example 2: Profile distortion in IPM - simulation



- Focus on beam field influence.
- Electrons "feel" beam fields (E) and their movement is influenced accordingly resulting in possible displacements.
- ≻ This occurs for large beam fields ↔ large charge densities, large beam energies.



Example 2: IPM profile corrections



- No simple mathematical procedure exists.
- Using higher electric and magnetic fields (expensive, sometimes impractical).
- Electric and magnetic fields : Sieve method (deconvolve with PSF of radius of Gyration).

[Dominik Vilsmeier, Bachelor Thesis, CERN]

Electric fields only: Several calibration/correction attempts.

Latest: Assumption on input beam distribution (Generalized Gaussian) and iterative procedure for input reconstruction from distorted profile using the data generated from simulation tool

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[Jan Egberts, PhD Thesis, CEA Saclay]
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Example 2: profile correction using ANN





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Validation "grid" (128 points)

- 4 validation data sets (inputs and outputs) created:
 > 1% off the training grid in each dimension (within in grid)
 > 25% off the training grid in each dimension
 > 50% off the training grid in each dimension
 > 100% off the training grid (the next point outside the grid)





Example 2: Results



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Example 2: Results

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Removing the validation sample outside of "training" area



For 12 runs: sigma systematically overestimated by 0.05% with error 0.7%



Conclusions



- > ML techniques become a standard tool for physicists and engineers.
- > They proof to be efficient in solving non-linear multivariate problems with unprecedented accuracy!
- Can save lots of money:

(CryoBLM project ~1 M€, a set of 1T magnets for IPM ~ 5M€)

- Modern tools (eg. tensorflow+keras) are very easy to use.
- Lot of physicists remain skeptical because "black box" nature of ML and lack of convincing way to estimate errors.
- Personally I think that we should use it but not forget about its limitations.



Further reading and playing



- "How could a Kangaroo climb Everest?" about minimization algorithms: ftp://ftp.sas.com/pub/neural/kangaroos
- > ANN recognizing drawings: https://quickdraw.withgoogle.com
- Music composed by AI: http://www.flow-machines.com/ai-makes-pop-music/
- Unreasonable effectiveness of ANN: http://karpathy.github.io/2015/05/21/rnn-effectiveness/
- > E. Musk concerned about AI: https://www.youtube.com/watch?v=0NTb10Au-Ic
- AI algorithms in social media very interesting: https://www.ted.com/talks/zeynep_tufekci_we_re_building_a_dystopia_just_to_make_pe ople_click_on_ads
- ANN playing with images: https://nerdist.com/why-are-googles-neural-networks-making-these-brain-melting-images

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